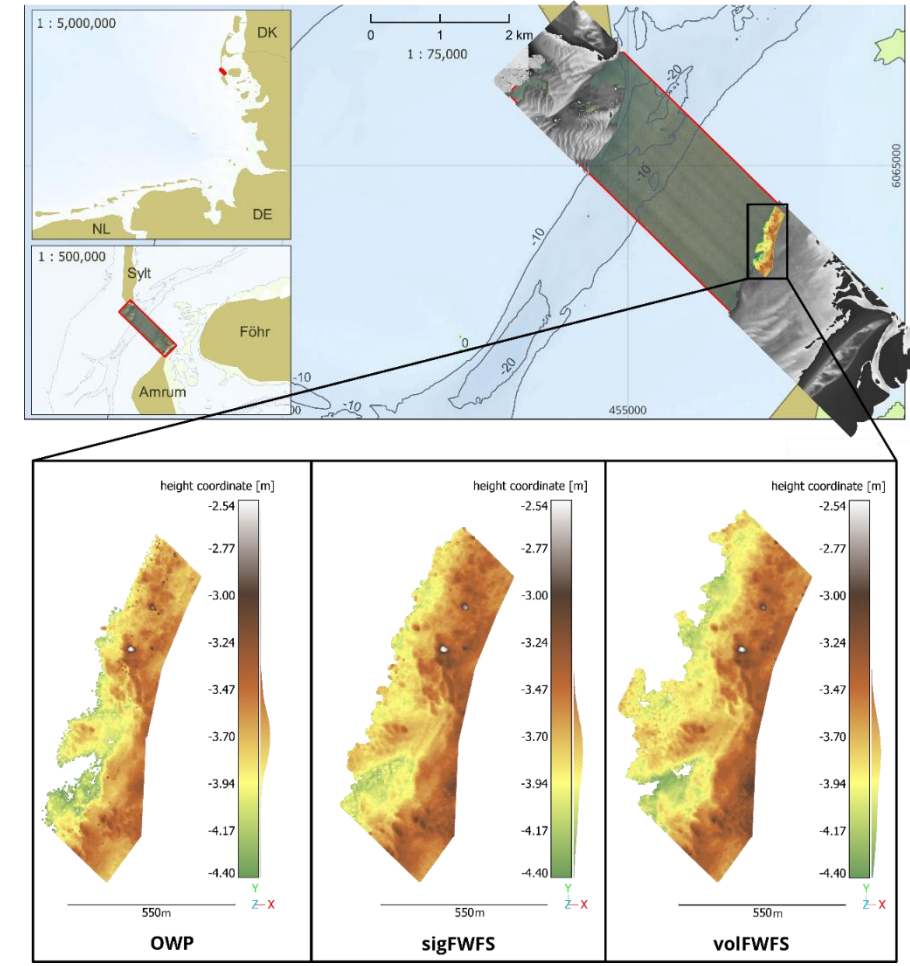
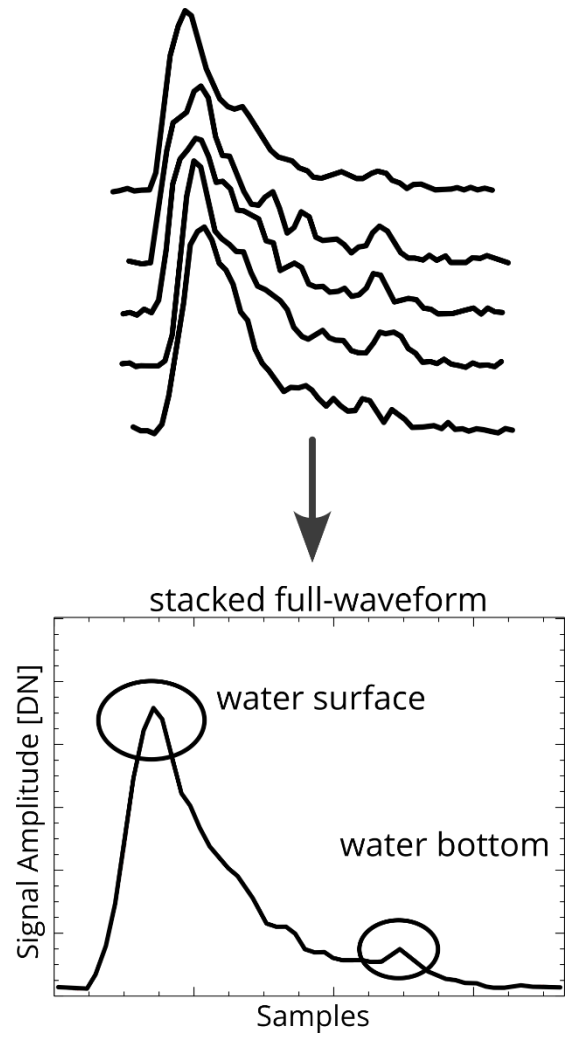
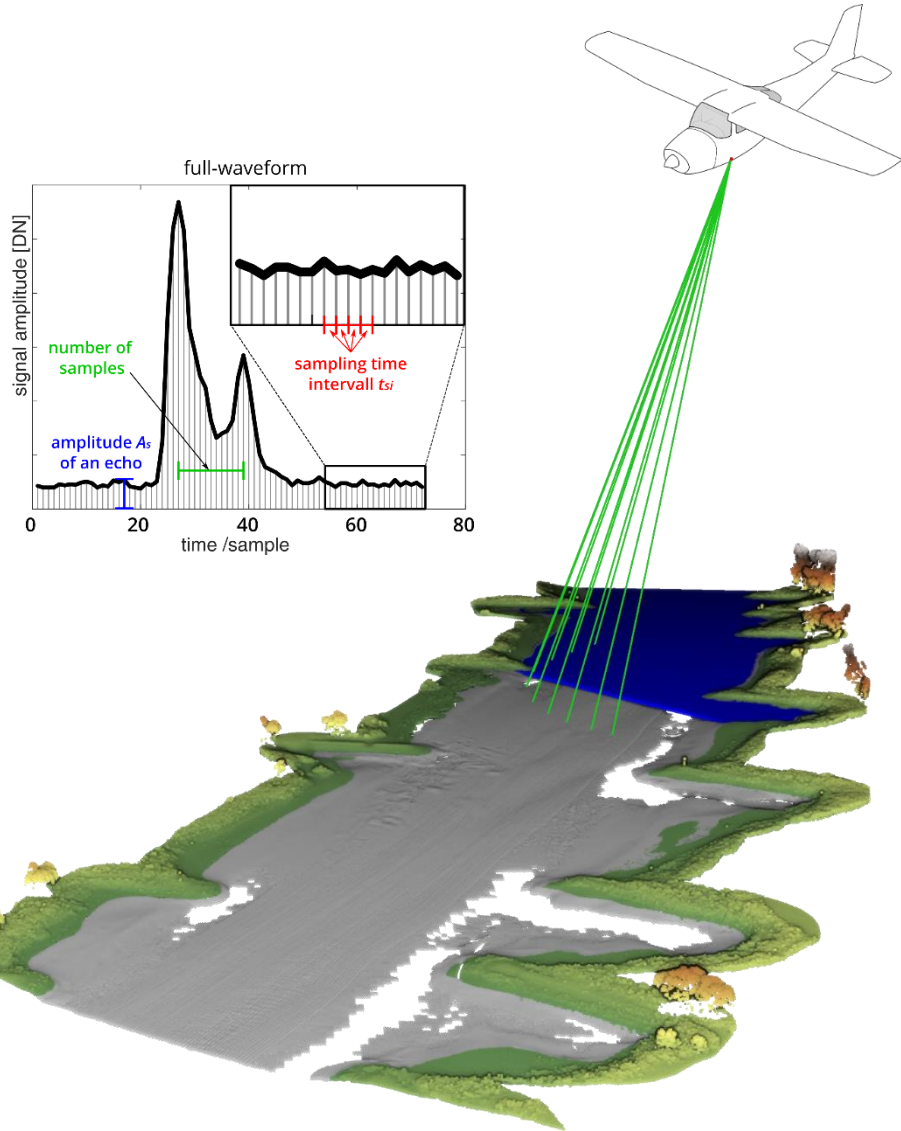


Institute of Photogrammetry and Remote Sensing
Chair of Photogrammetry

Full-waveform stacking techniques applied to coastal LiDAR bathymetry data

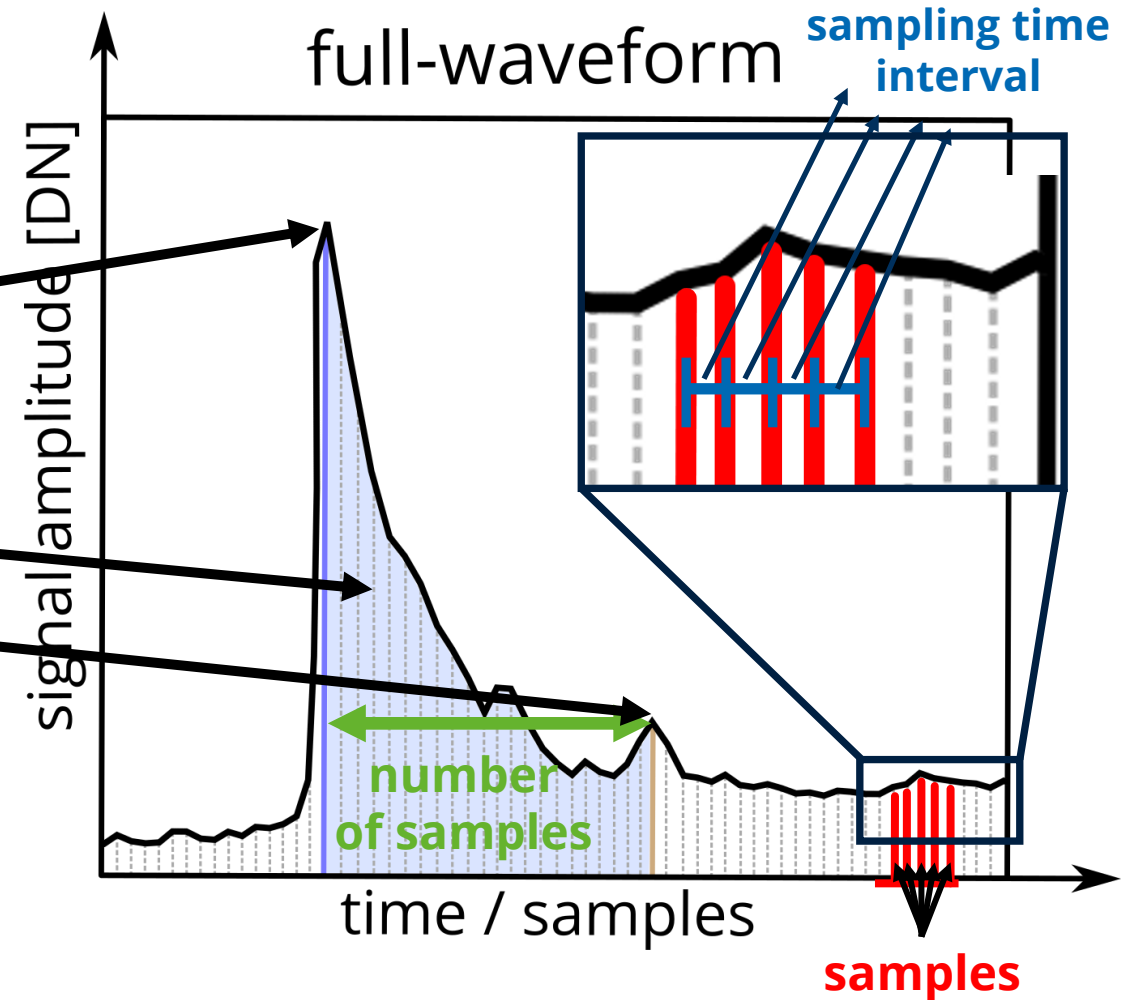
David Mader, Katja Richter, Patrick Westfeld, Hans-Gerd Maas
HYDRO2024, Rostock-Warnemünde, 05 Nov 2024

Content



Measurement principle - airborne laser bathymetry (ALB)

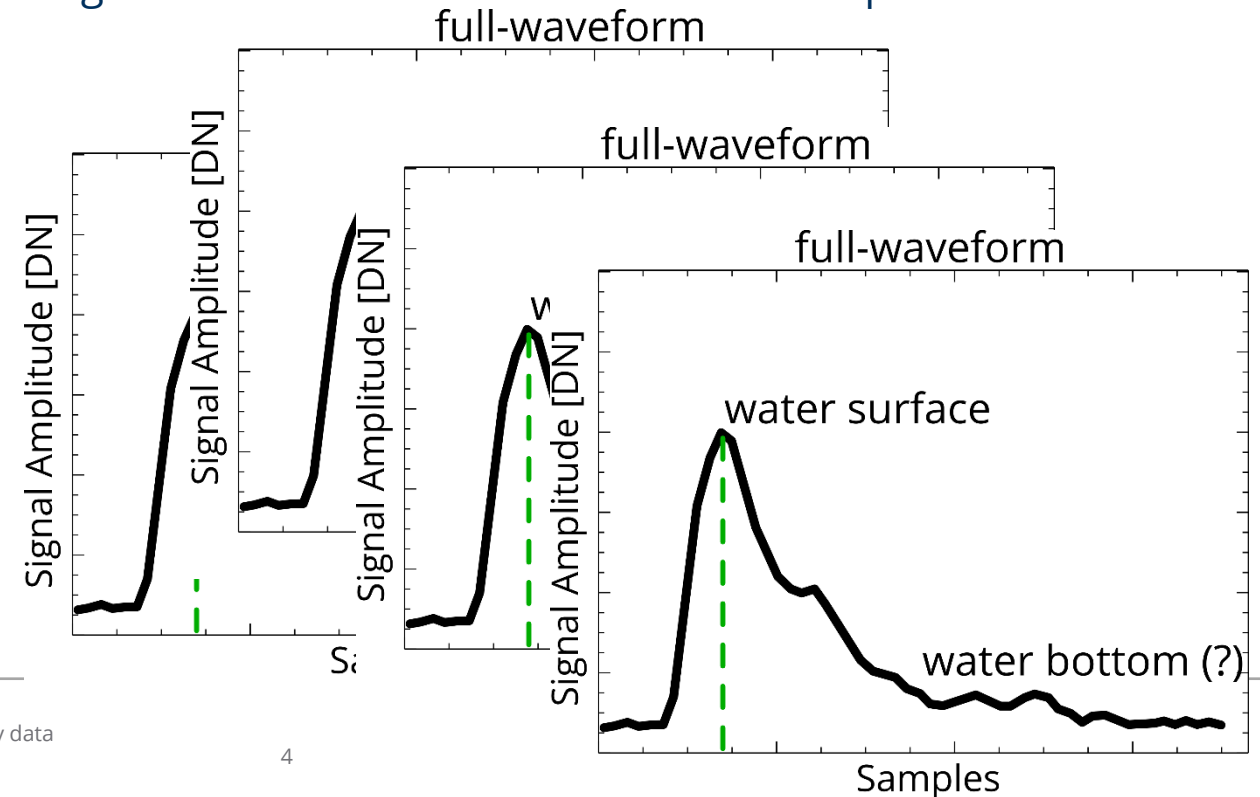
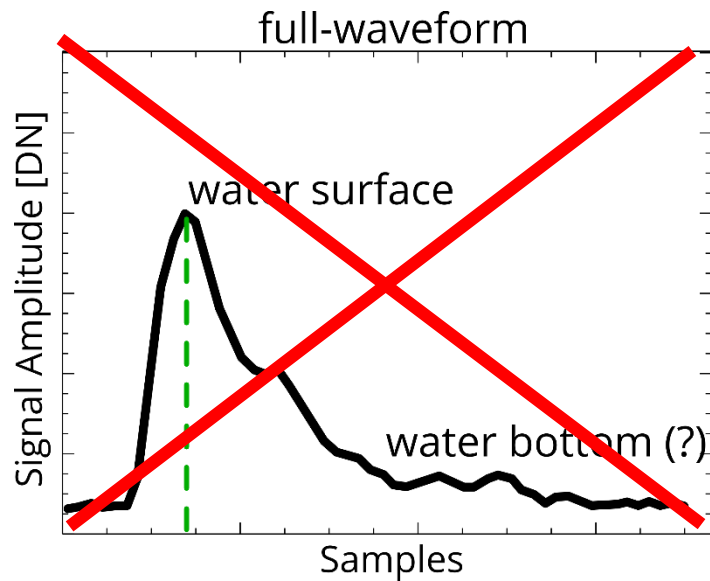
- time-of-flight principle $D = c \cdot \frac{t_{rt}}{2}$
- usage of green laser pulse (532nm)
- full-waveform = Recording and digitizing of the interactions of a laser pulse with:
 - water surface
 - water column
 - water bottom
- full-waveform consists of samples with constant sampling time interval



Advanced methods for determining water bottom points

- basic principle:

- assumption: closely neighboring measurement data have very similar characteristics in terms of water depth (with steady water bottoms)
- no isolated evaluation of the measurement data
- combined evaluation of spatially closely neighboring measurement data to derive water depth information





ORIGINAL ARTICLE



Potential of a Non-linear Full-Waveform Stacking Technique in Airborne LiDAR Bathymetry

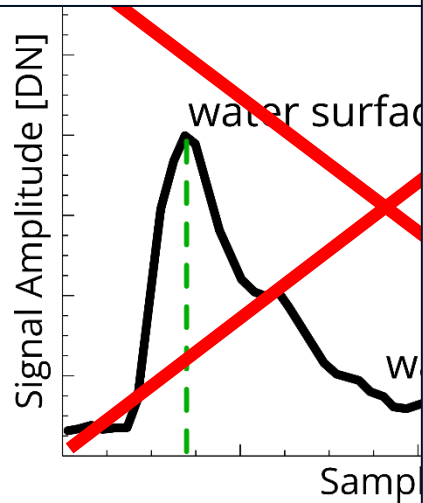
Demonstration of Full-Waveform Stacking Techniques on Data from the Elbe River

David Mader¹ · Katja Richter¹ · Patrick Westfeld² · Hans-Gerd Maas¹

Received: 29 December 2020 / Accepted: [unclear]
© The Author(s) 2021, corrected publication [unclear]

cs in terms of water

water depth



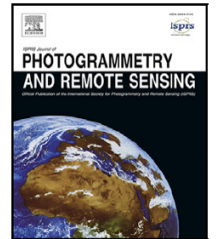
ISPRS Journal of Photogrammetry and Remote Sensing 204 (2023) 145–162



Contents lists available at [ScienceDirect](https://www.sciencedirect.com)

ISPRS Journal of Photogrammetry and Remote Sensing

journal homepage: www.elsevier.com/locate/isprsjprs

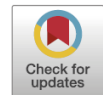


Volumetric nonlinear ortho full-waveform stacking in airborne LiDAR bathymetry for reliable water bottom point detection in shallow waters

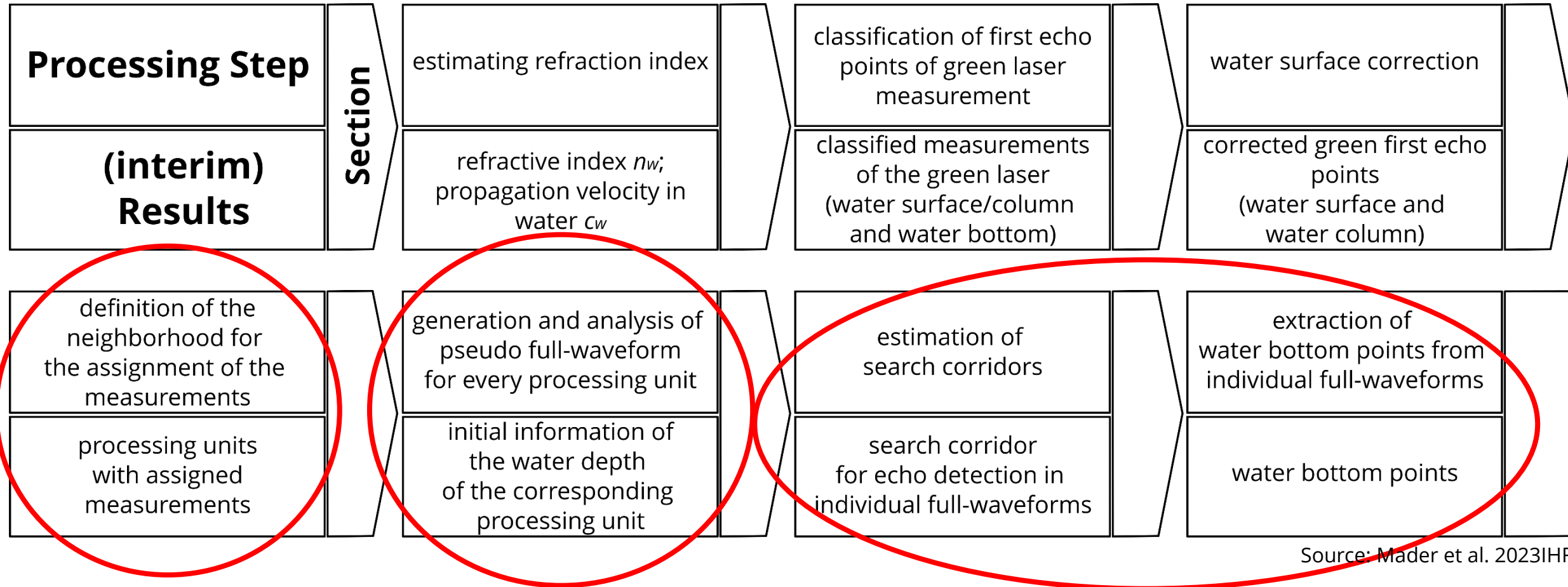
D. Mader^{a,*}, K. Richter^a, P. Westfeld^b, H.-G. Maas^a

^a Institute of Photogrammetry and Remote Sensing, Dresden University of Technology, Helmholtzstraße 10, 01069 Dresden, Germany

^b Federal Maritime and Hydrographic Agency of Germany (BSH), Neptunallee 5, 18057 Rostock, Germany



Advanced methods – full-waveform stacking



Source: Mader et al. 2023IHR

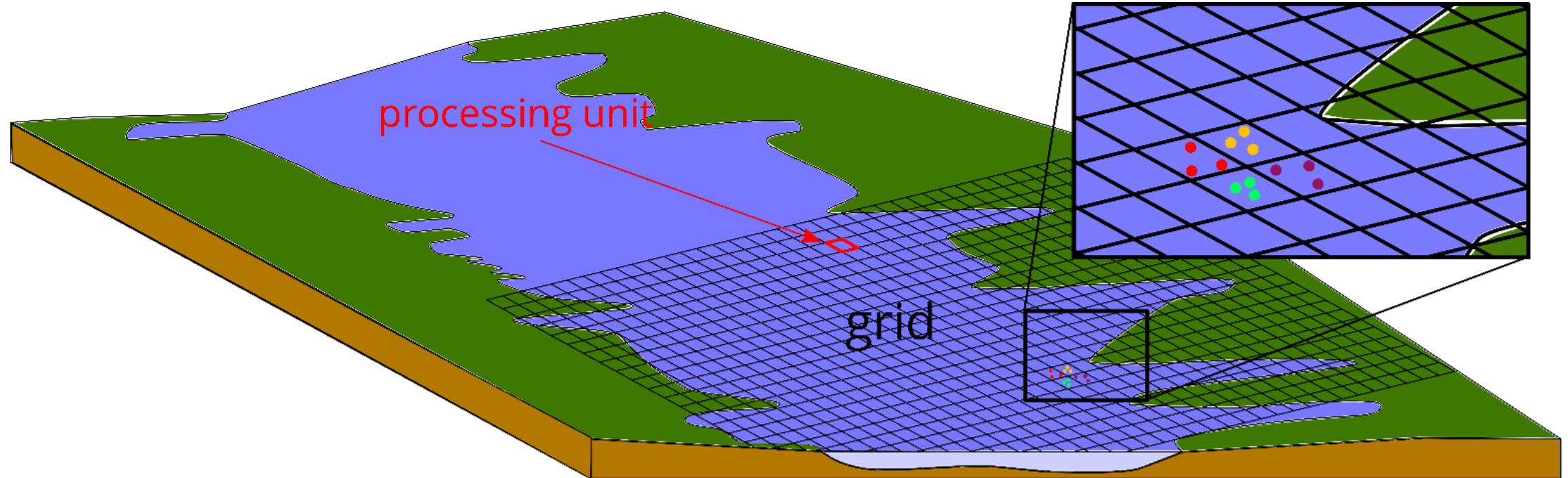
Potential of a Non-linear Full-Waveform Stacking Technique in Airborne LiDAR Bathymetry

Demonstration of Full-Waveform Stacking Techniques on Data from the Elbe River

David Mader¹ · Katja Richter¹ · Patrick Westfeld² · Hans-Gerd Maas¹

Advanced methods – signal-based fwf stacking (1) (sigFWFS)

- definition of neighborhood is based on position of first echo point
- partitioning of survey data in a regular grid
- combined processing of all survey data within a grid cell



Source: Mader et al. 2023IHR

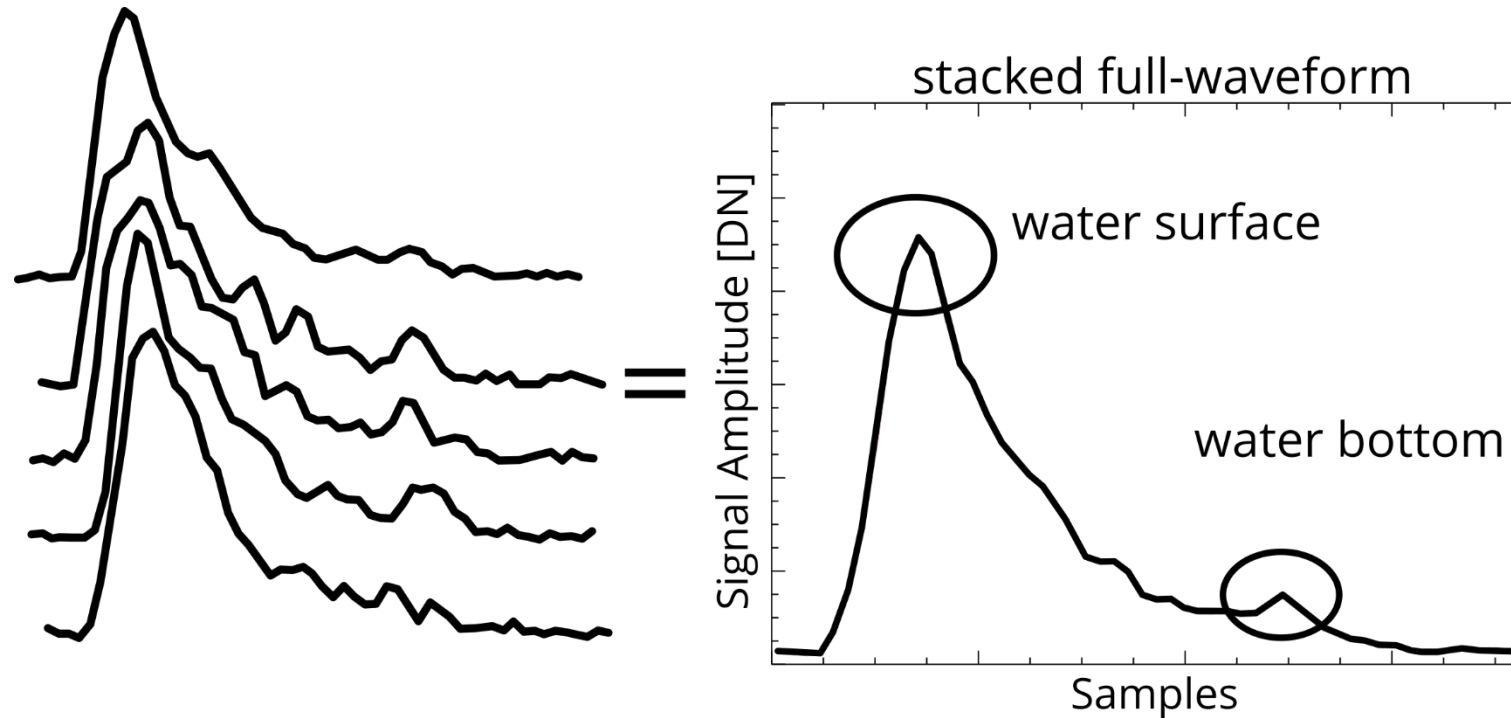
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David Mader¹ · Katja Richter¹ · Patrick Westfeld² · Hans-Gerd Maas¹

Advanced methods – signal-based fwf stacking (2) (sigFWFS)

- alignment of full-waveforms
- accumulation of individual full-waveform to stacked full-waveform
- stacked full-waveform has an improved signal-to-noise ratio



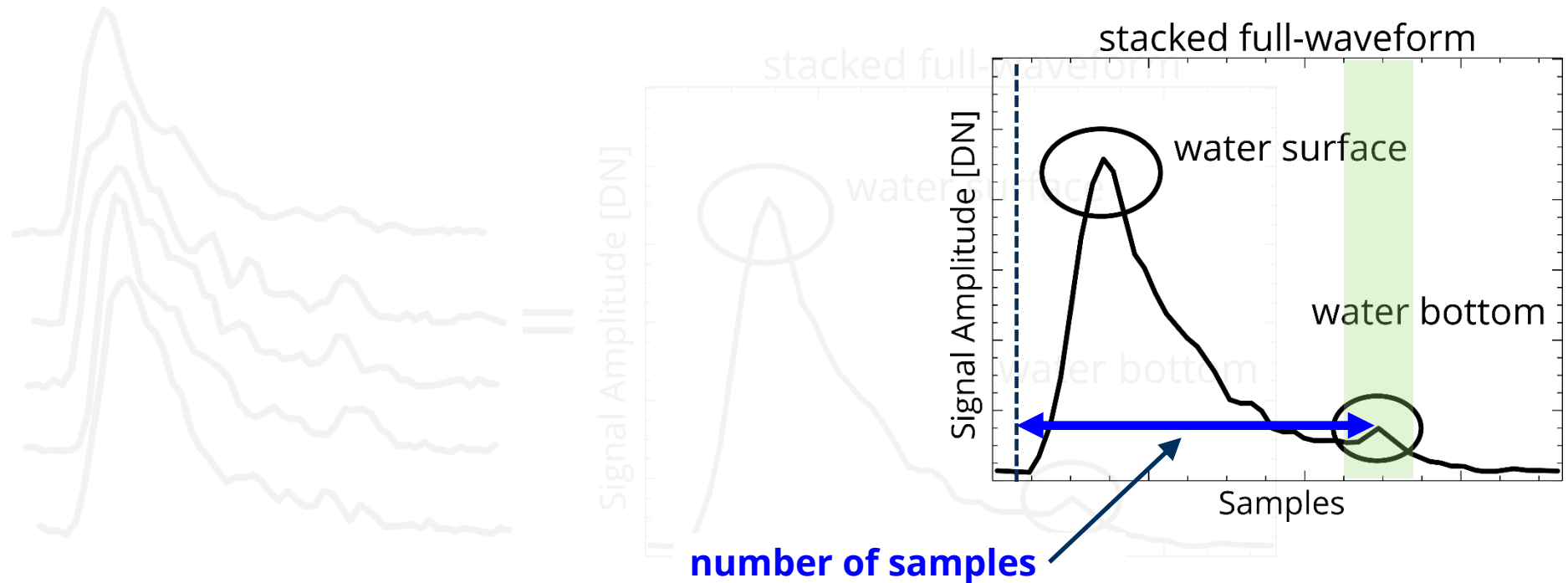
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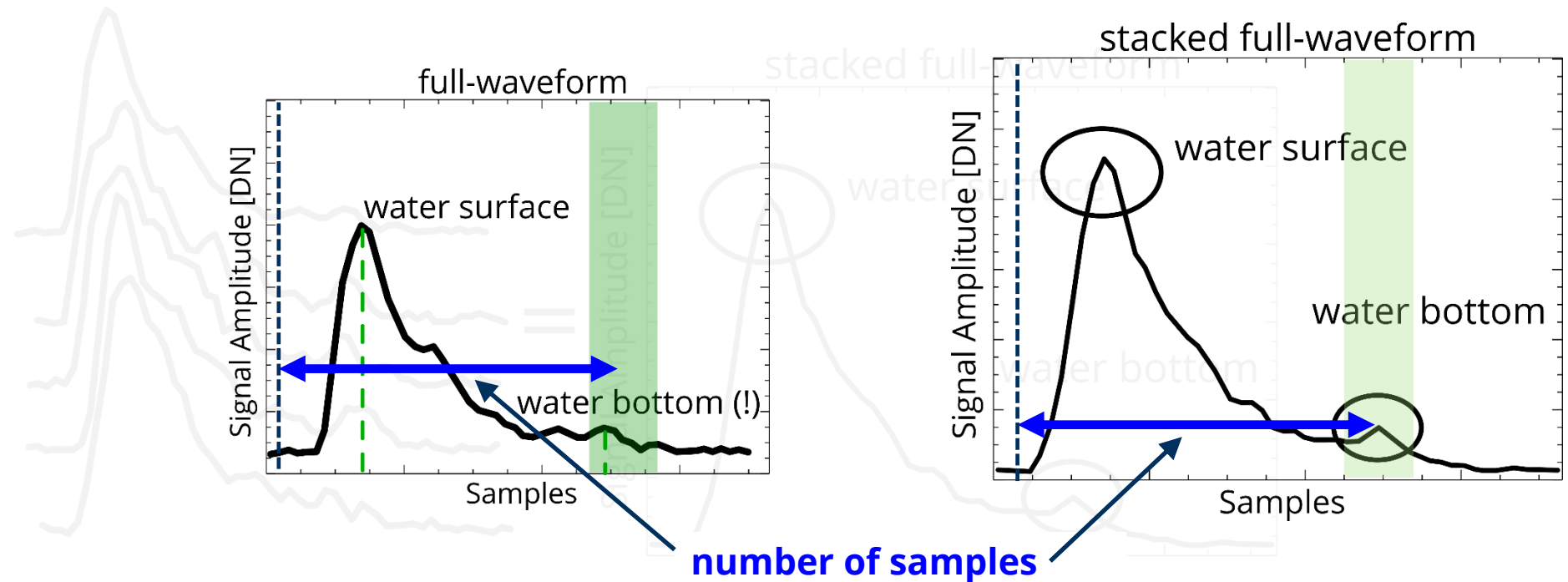
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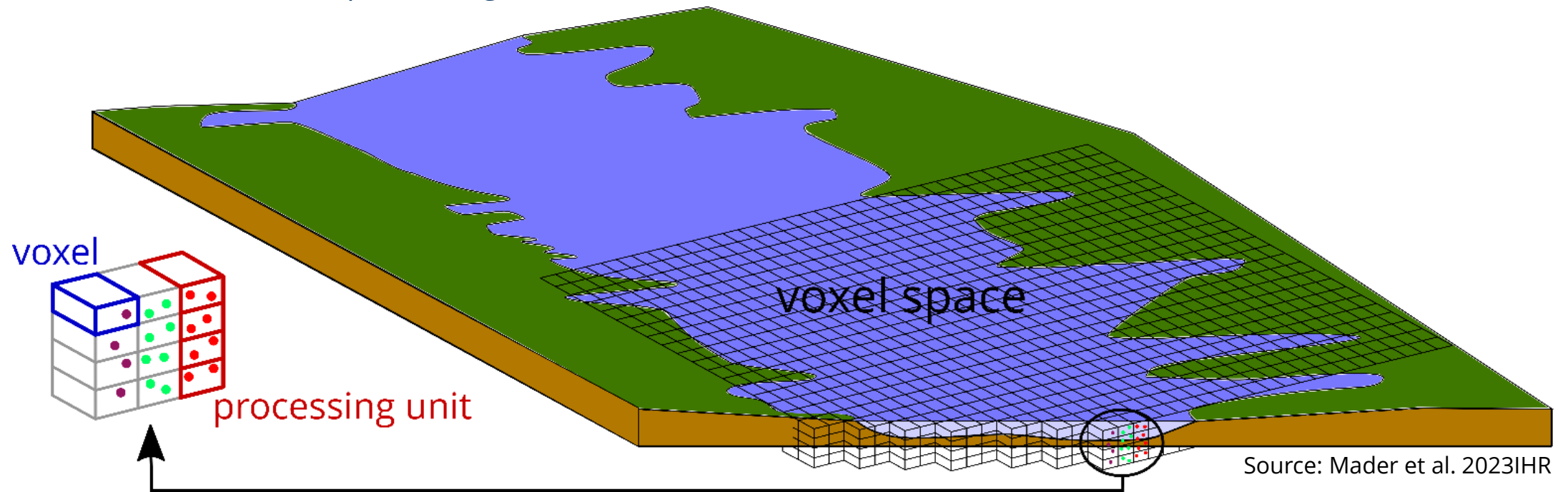


Volumetric nonlinear ortho full-waveform stacking in airborne LiDAR bathymetry for reliable water bottom point detection in shallow waters

D. Mader^{a,*}, K. Richter^a, P. Westfeld^b, H.-G. Maas^a

Advanced methods – volumetric fwf stacking (1) (voIFWFS)

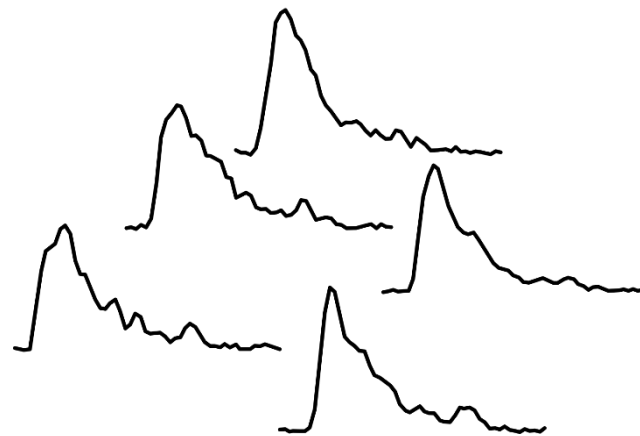
- integration of all full-waveform information into the voxel space (mapping of amplitudes)
- close neighborhood is guaranteed along the entire water column
- water/voxel column = processing unit



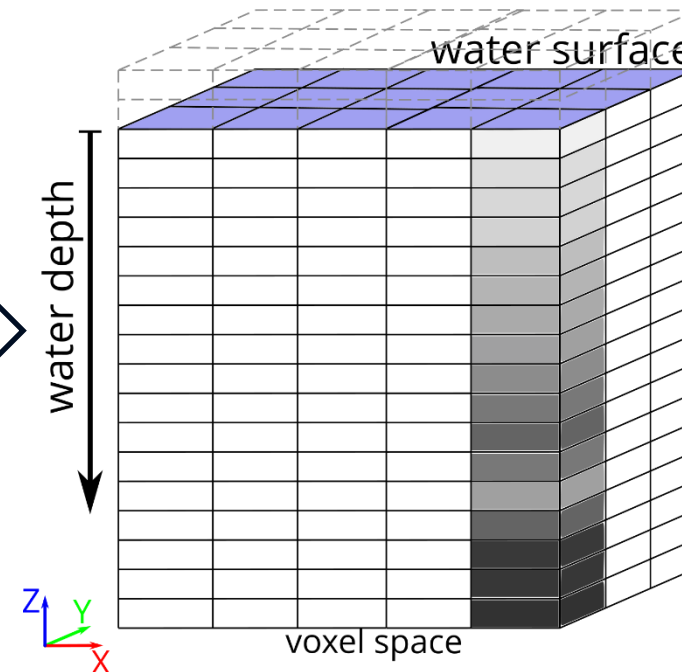
Advanced methods – volumetric fwf stacking (2) (voFWFS)

- mapping of full-waveform sample information into the voxel space
- generation of an ortho full-waveform
- ortho full-waveform has an improved signal-to-noise ratio

individual full-waveforms



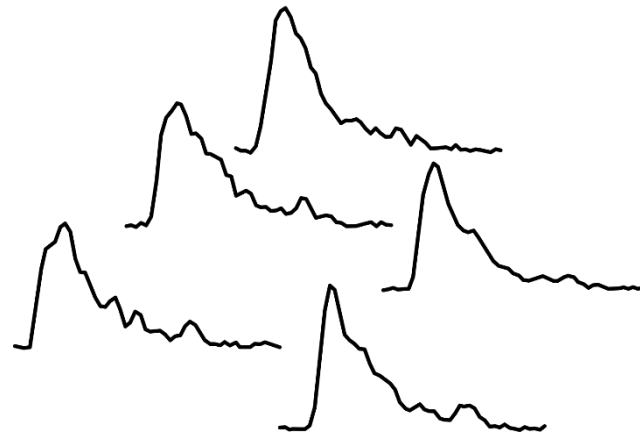
samplewise



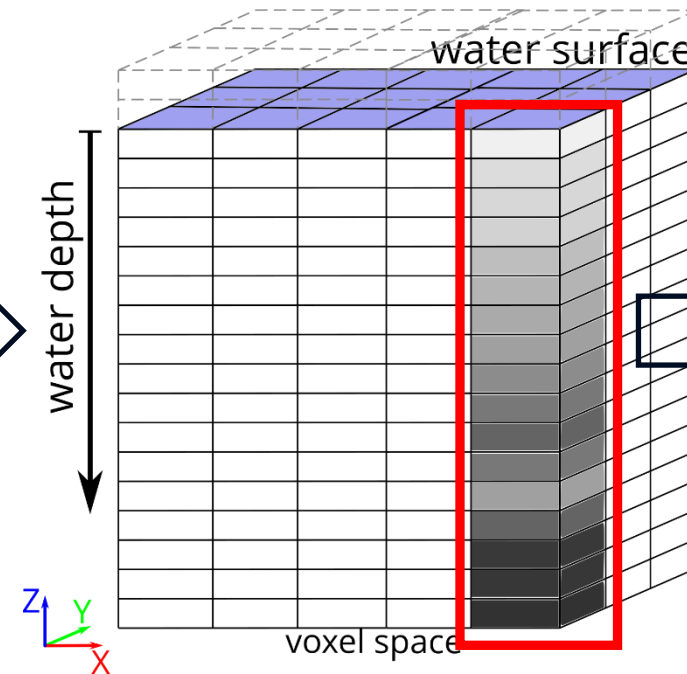
Advanced methods – volumetric fwf stacking (2) (voFWFS)

- mapping of full-waveform sample information into the voxel space
- generation of an ortho full-waveform
- ortho full-waveform has an improved signal-to-noise ratio

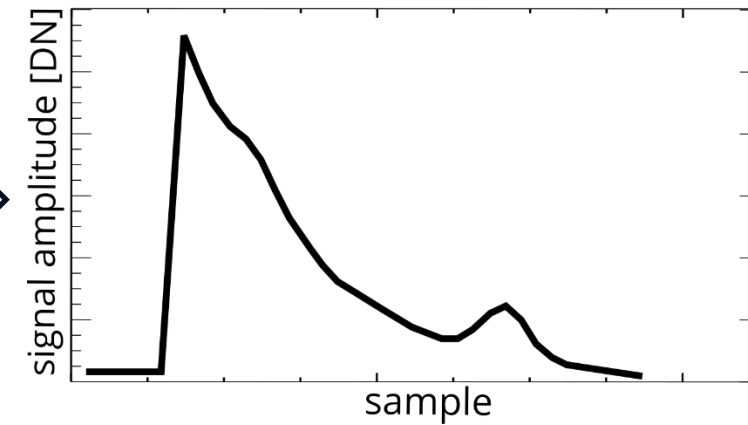
individual full-waveforms



samplewise



ortho waveform

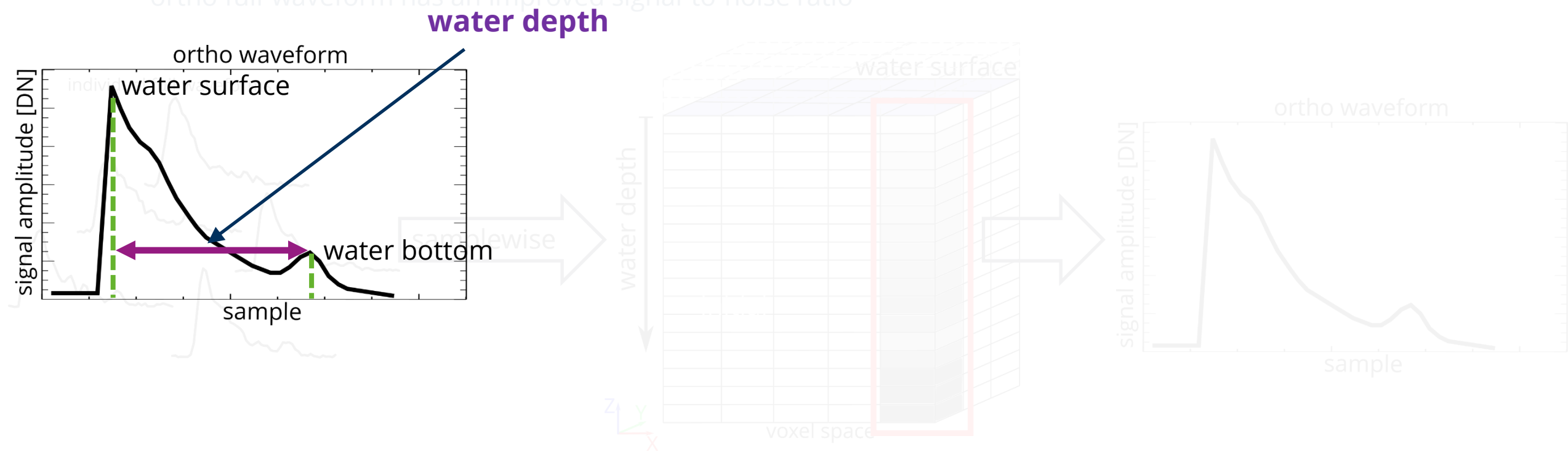


Volumetric nonlinear ortho full-waveform stacking in airborne LiDAR bathymetry for reliable water bottom point detection in shallow waters

D. Mader^{a,*}, K. Richter^a, P. Westfeld^b, H.-G. Maas^a

Advanced methods – volumetric fwf stacking (2) (volFWFS)

- mapping of full-waveform sample information into the voxel space
- generation of an ortho full-waveform
- ortho full-waveform has an improved signal-to-noise ratio

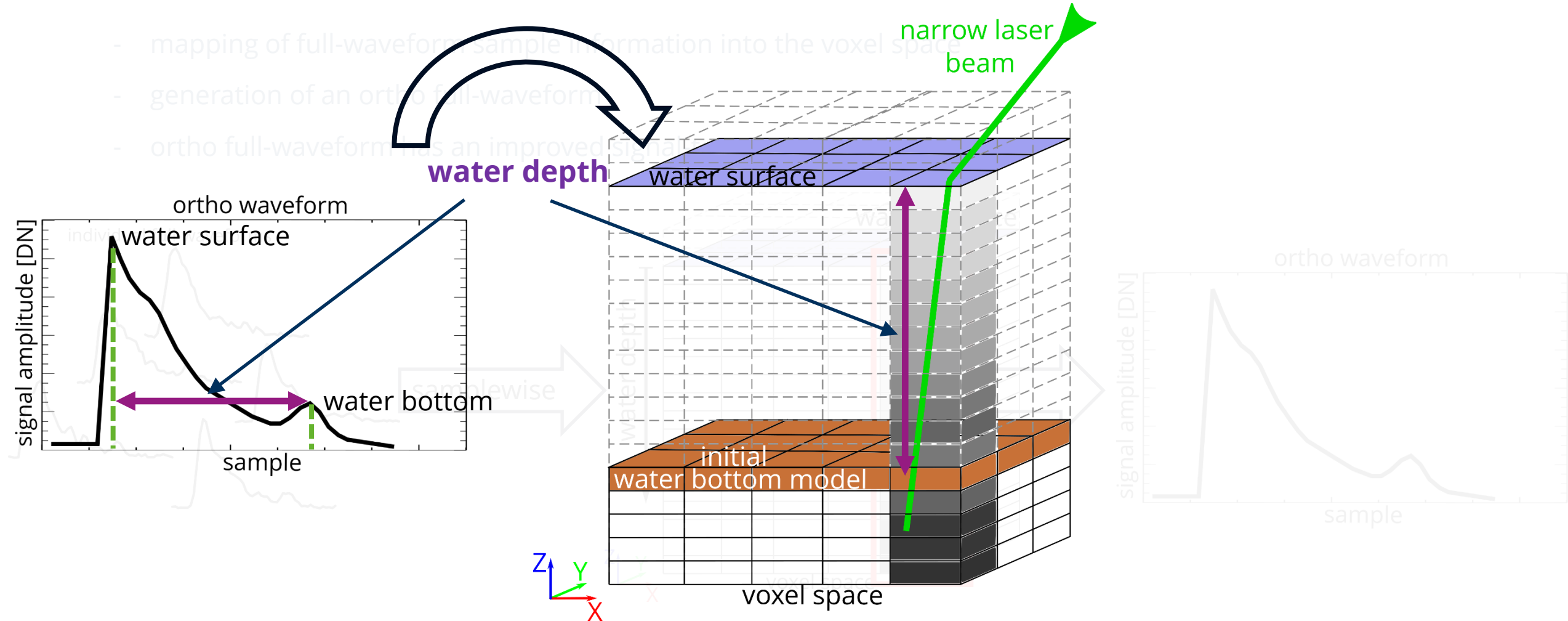


Volumetric nonlinear ortho full-waveform stacking in airborne LiDAR bathymetry for reliable water bottom point detection in shallow waters

D. Mader^{a,*}, K. Richter^a, P. Westfeld^b, H.-G. Maas^a

Advanced methods – volumetric fwf stacking (2) (volFWFS)

- mapping of full-waveform sample information into the voxel space
- generation of an ortho full-waveform
- ortho full-waveform has an improved signal

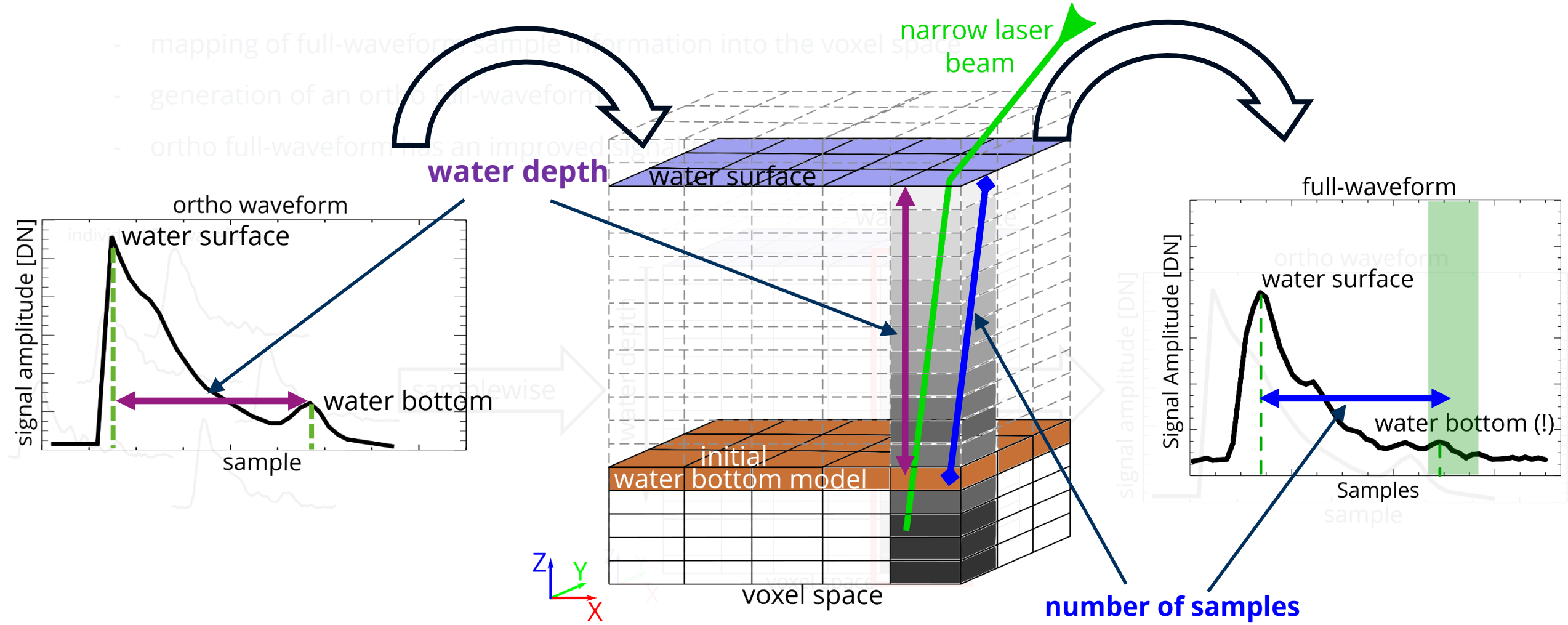


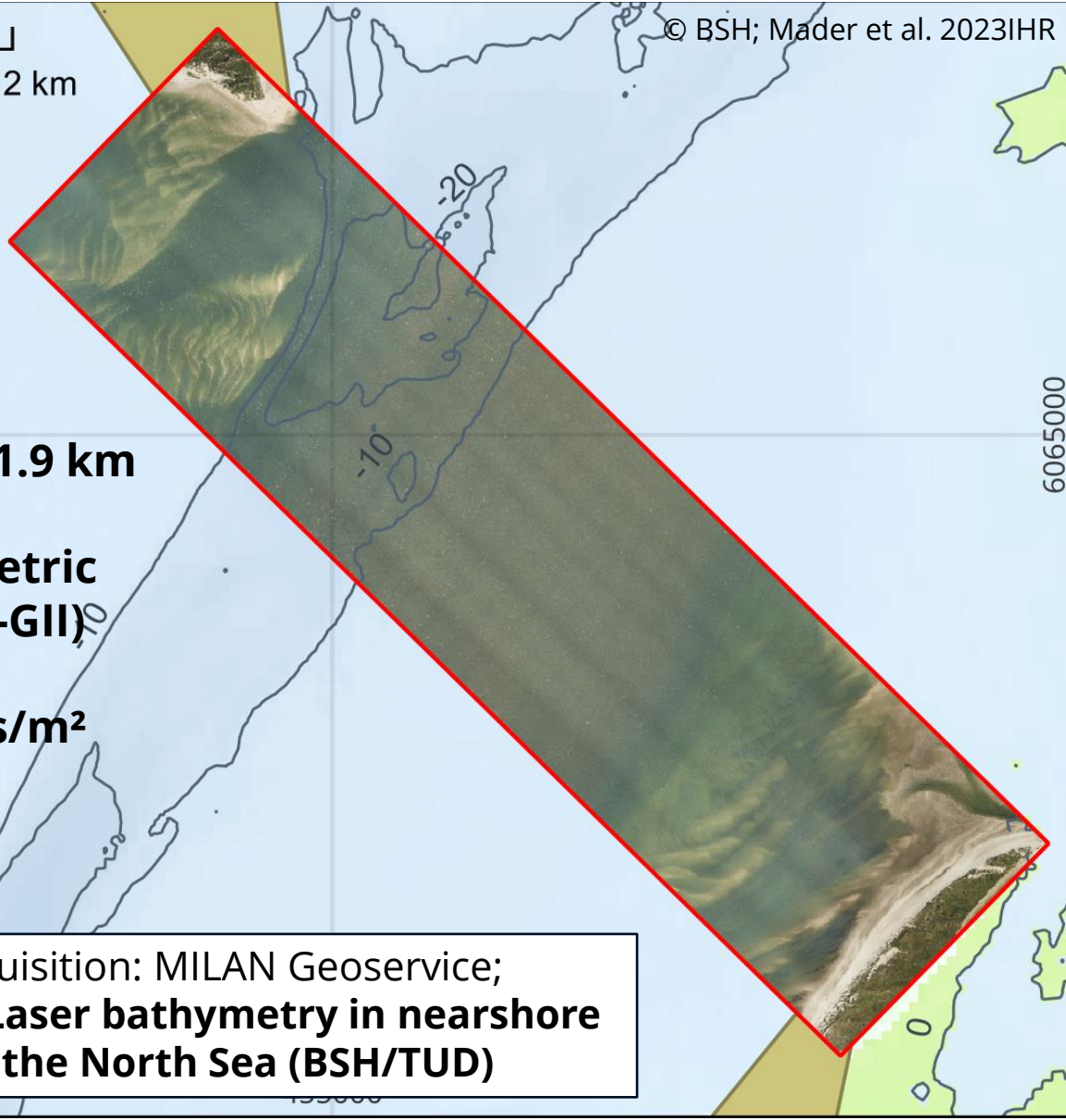
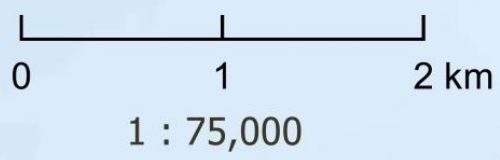
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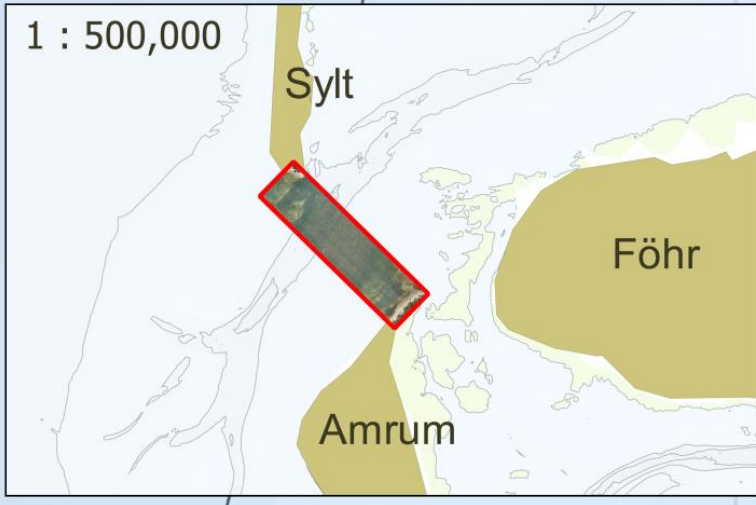
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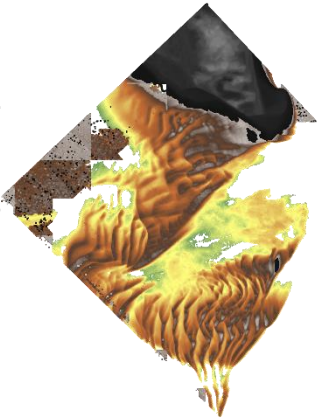
- covered area: 7.5km x 1.9 km
- shallow water bathymetric scanner (RIEGL VQ-880-GII)
- per scan strip 13-19 pts/m²



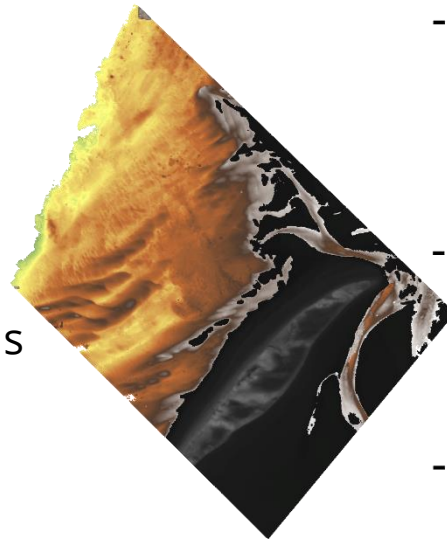
Data acquisition: MILAN Geoservice;
Project: **Laser bathymetry in nearshore areas of the North Sea (BSH/TUD)**

Laser bathymetry in nearshore areas of the North Sea (BSH/TUD)

Source: Mader et al. 2023IHR



height coordinate [m]

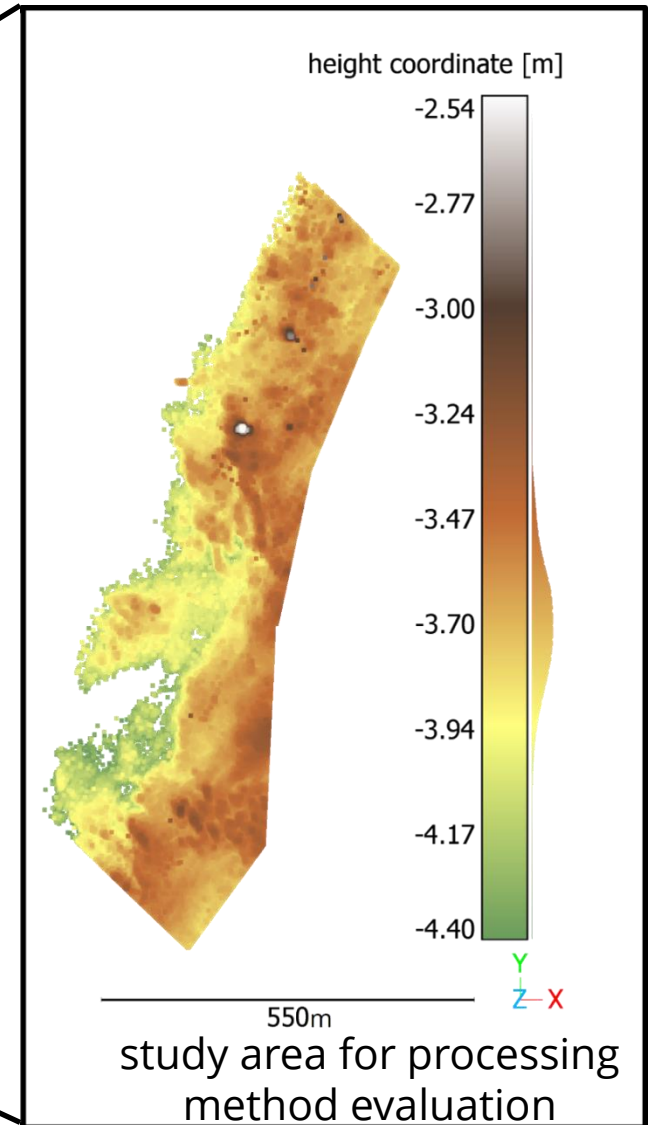
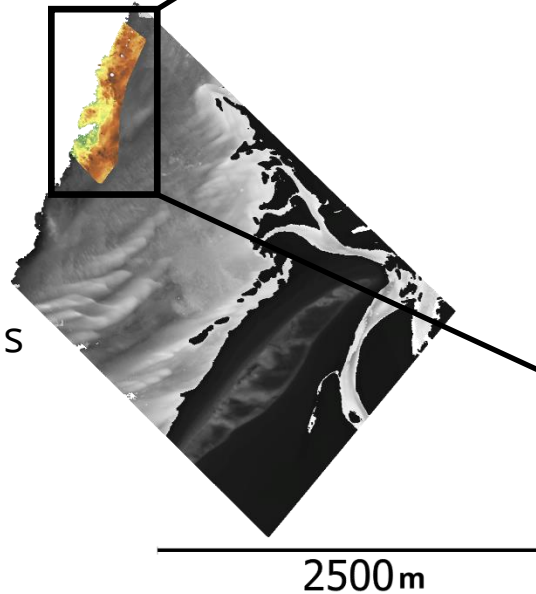
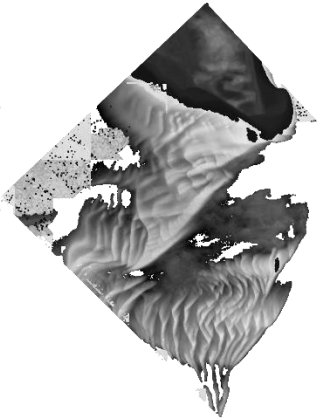


2500m

- standard processing methods
- reached water depth 2.87m
- aim: reduction of data gap

Laser bathymetry in nearshore areas of the North Sea (BSH/TUD)

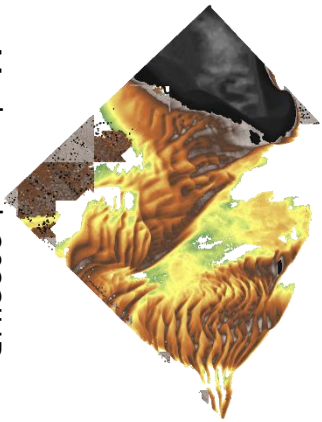
Source: Mader et al. 2023IHR



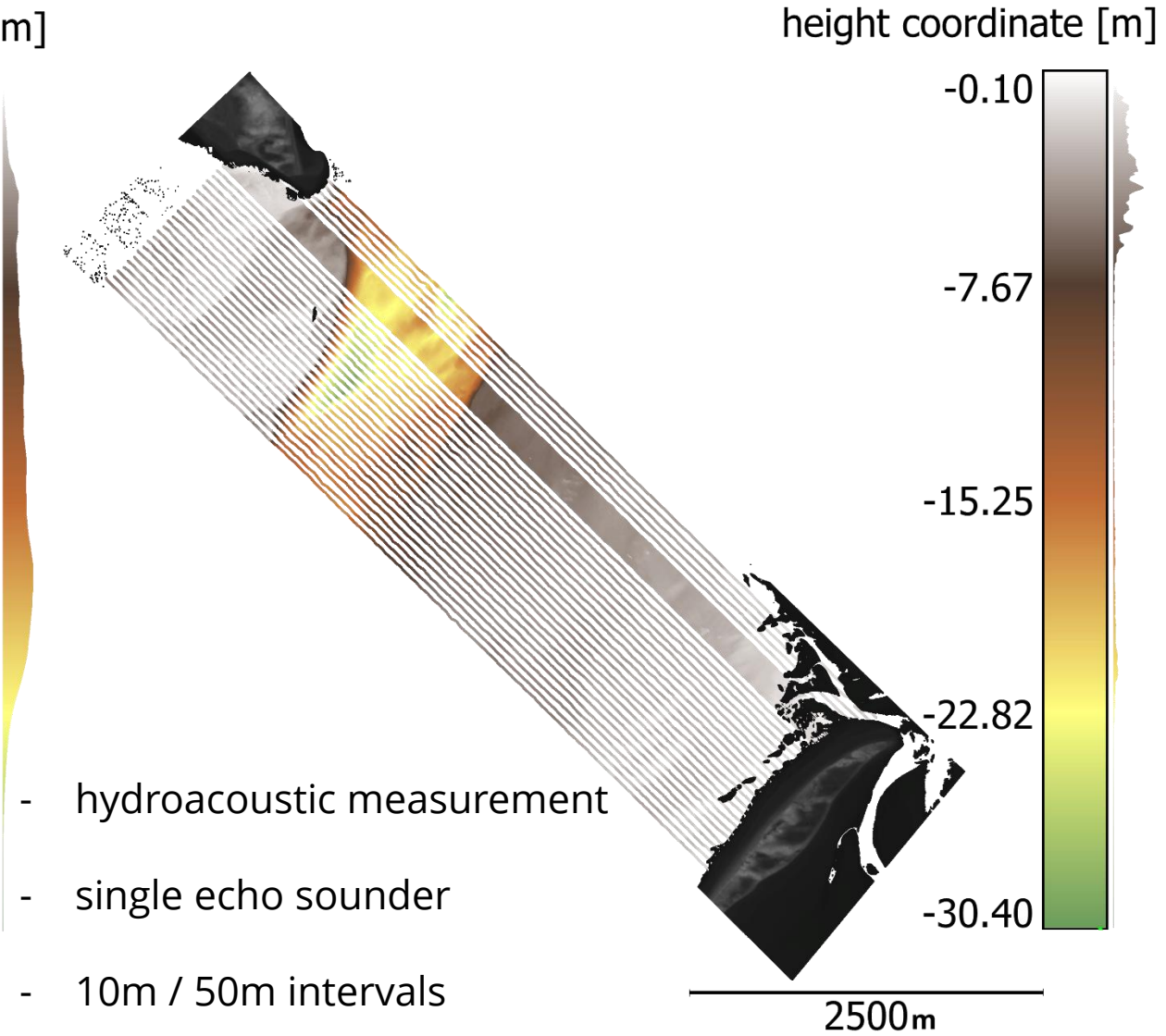
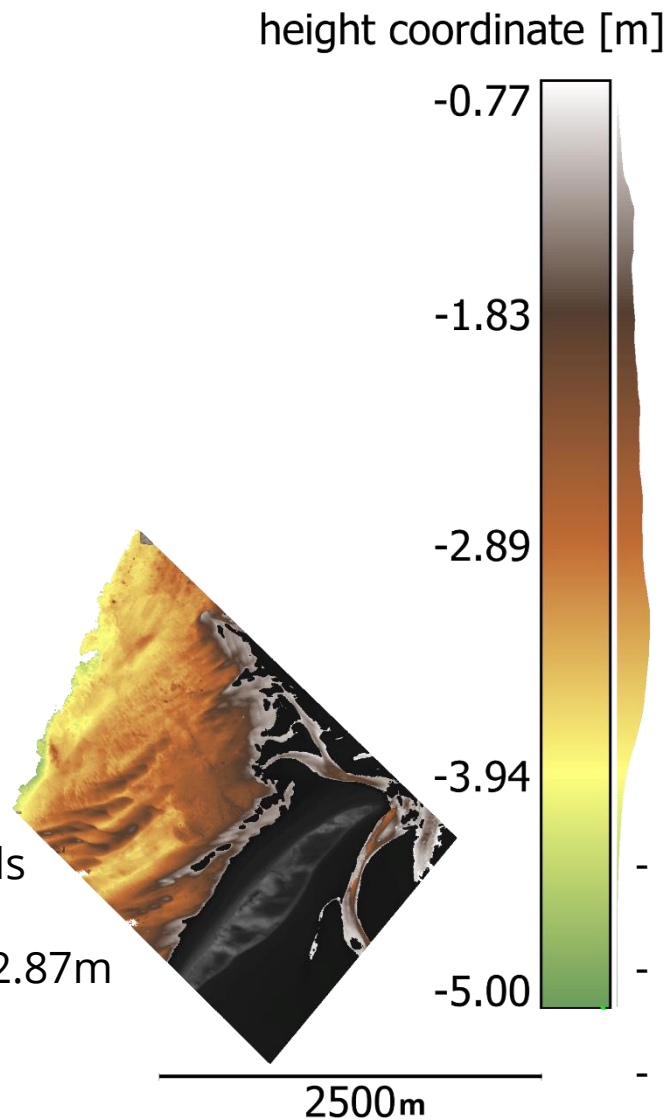
- standard processing methods
- reached water depth 2.87m
- aim: reduction of data gap

Laser bathymetry in nearshore areas of the North Sea (BSH/TUD)

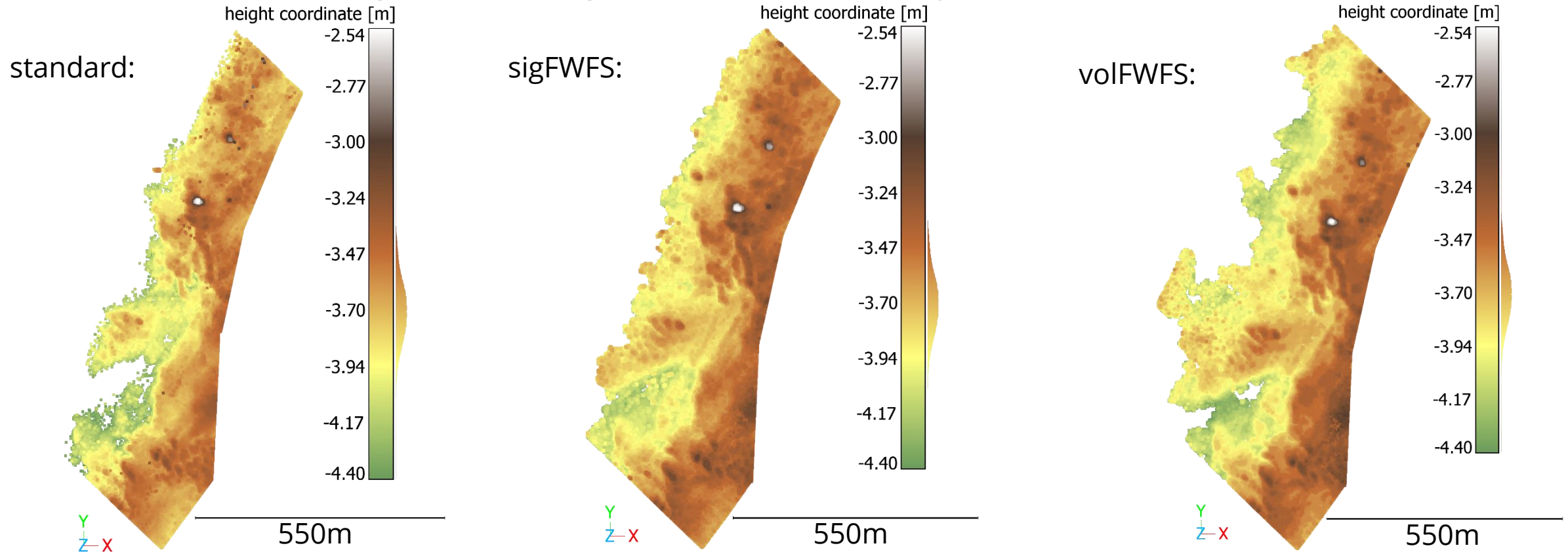
Source: Mader et al. 2023IHR



- standard processing methods
- reached water depth about 2.87m
- aim: reduction of data gap



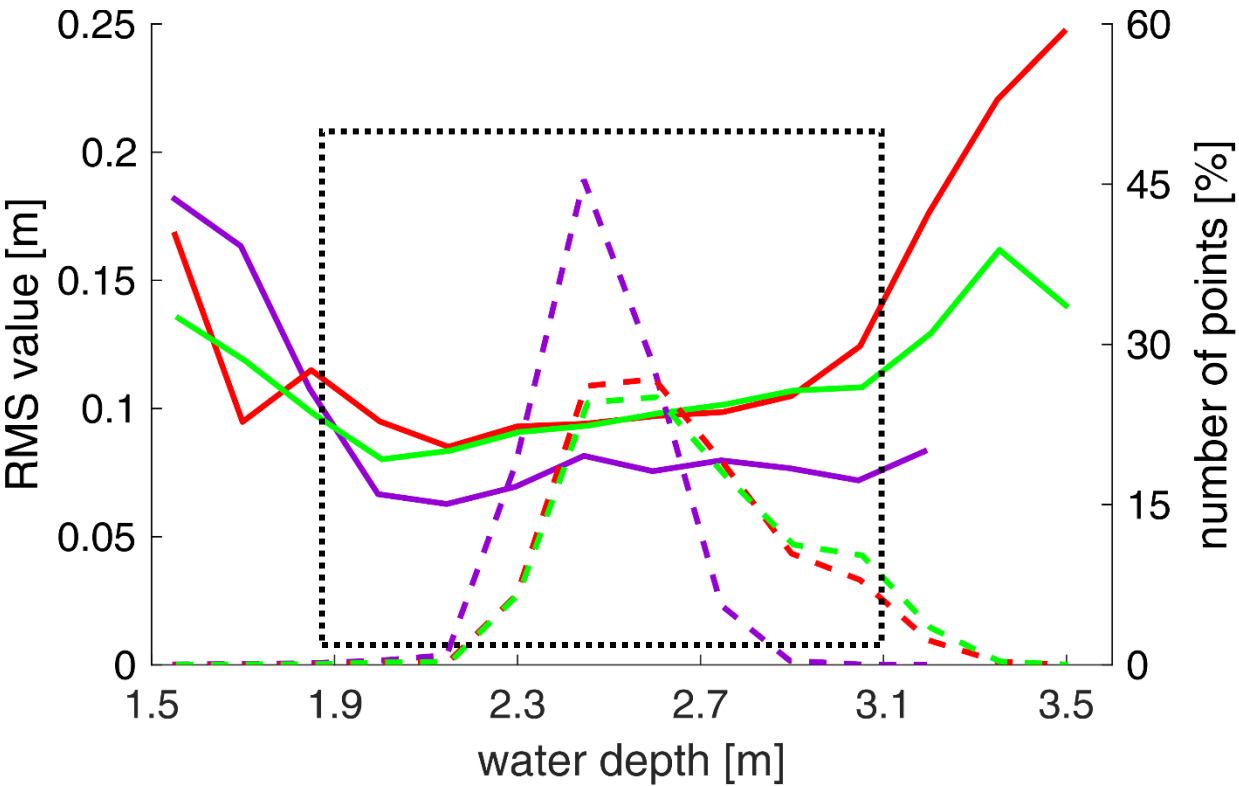
Results – comparison of point cloud with hydroacoustic measurements



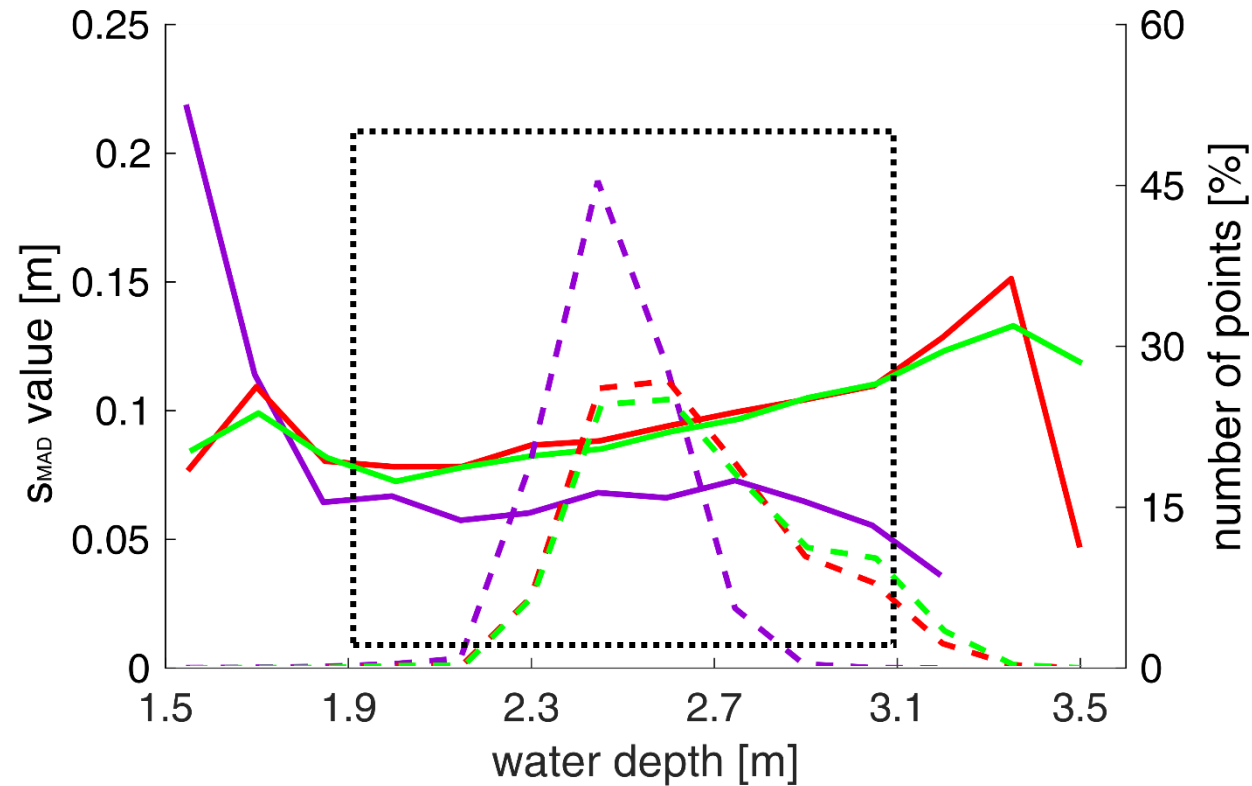
Source: Mader et al. 2023IHR

| | $\overline{\Delta h}$ | $s_{\overline{\Delta h}}$ | RMS | σ_{MAD} | $ \overline{\Delta h} \leq 25 \text{ cm}$ TVU special order |
|----------|-----------------------|---------------------------|---------|----------------|--|
| standard | 0.036 m | 0.069 m | 0.078 m | 0.067 m | 99.55 % |
| sigFWFS | 0.00024 m | 0.103 m | 0.103 m | 0.099 m | 98.44 % |
| volFWFS | 0.0099 m | 0.100 m | 0.101 m | 0.096 m | 98.68 % |

Results – accuracy and reliability as a function of the water depth



RMS: — OWP — sigFWFS — volFWFS
 number of points: - - - OWP - - - sigFWFS - - - volFWFS

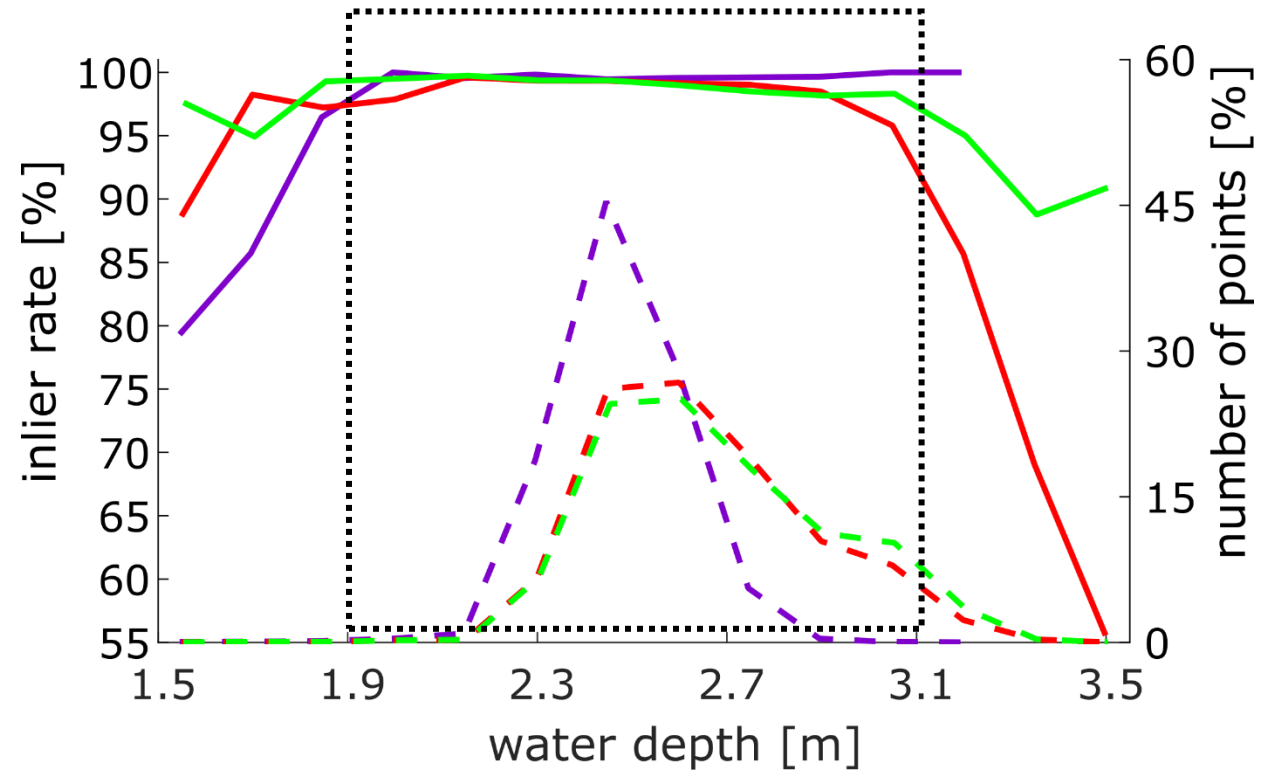
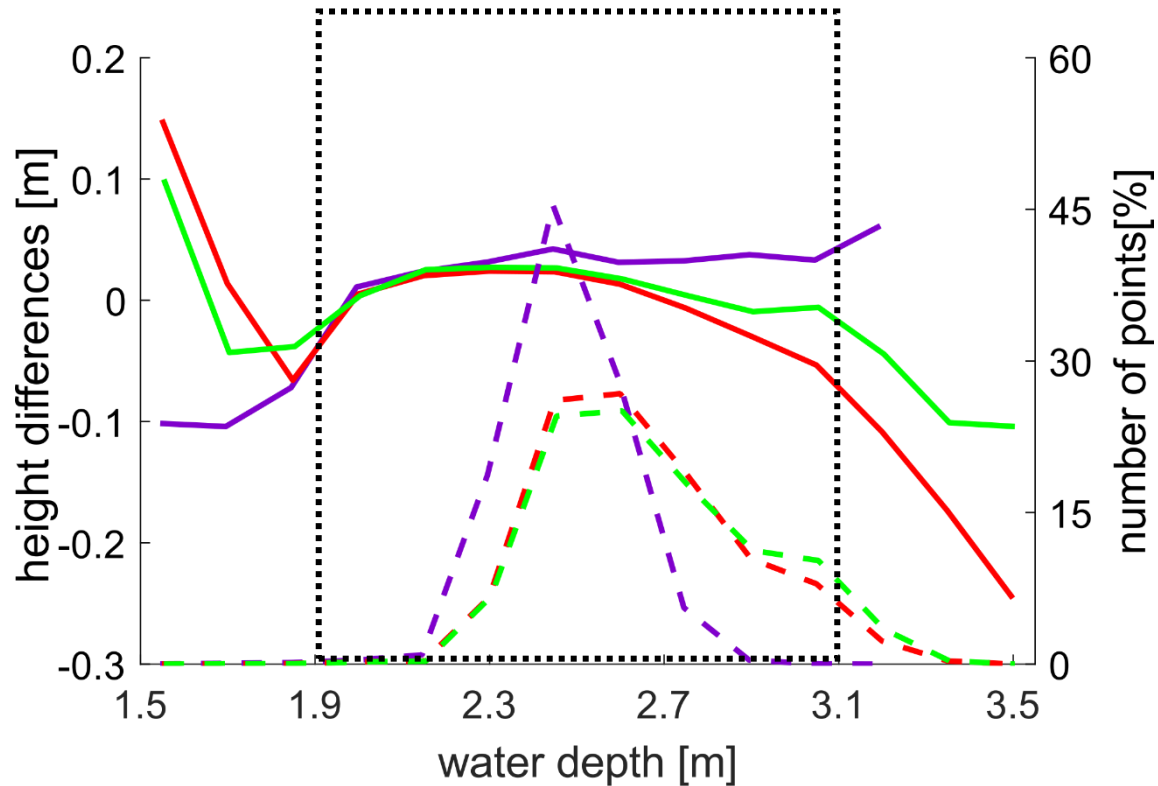


SMAD: — OWP — sigFWFS — volFWFS
 number of points: - - - OWP - - - sigFWFS - - - volFWFS

(OWP = standard processing)

Source: Mader et al. 2023IHR

Results – accuracy and reliability as a function of the water depth



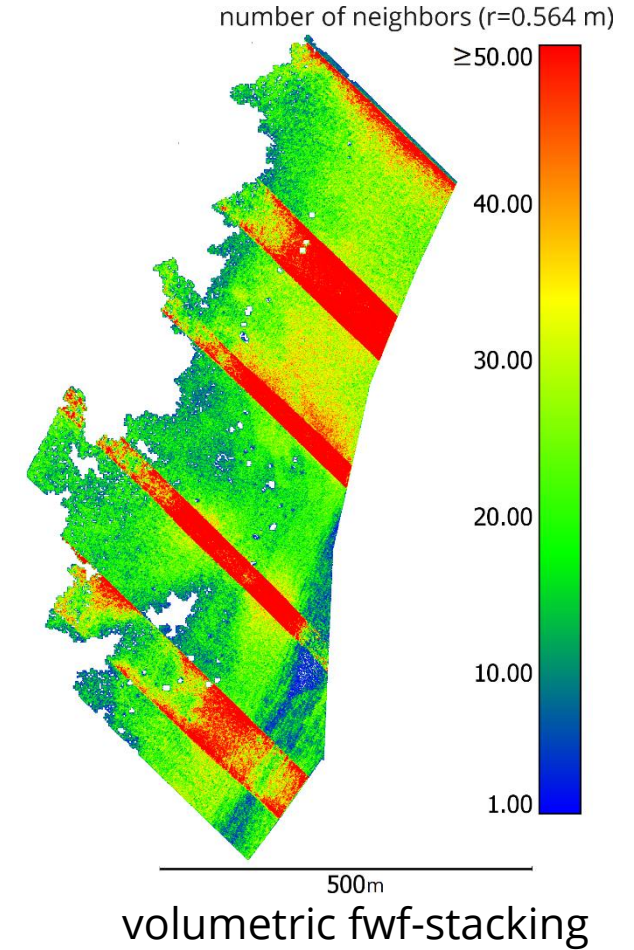
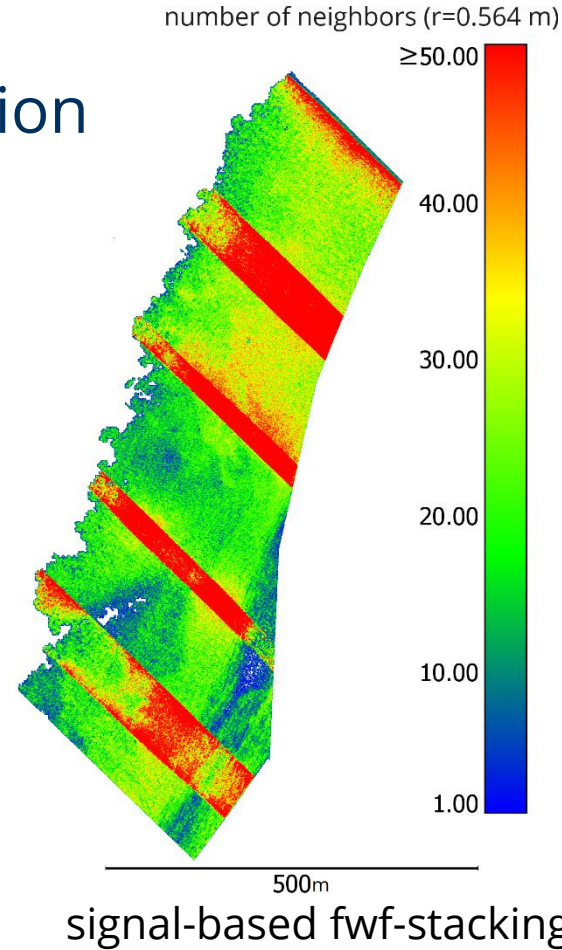
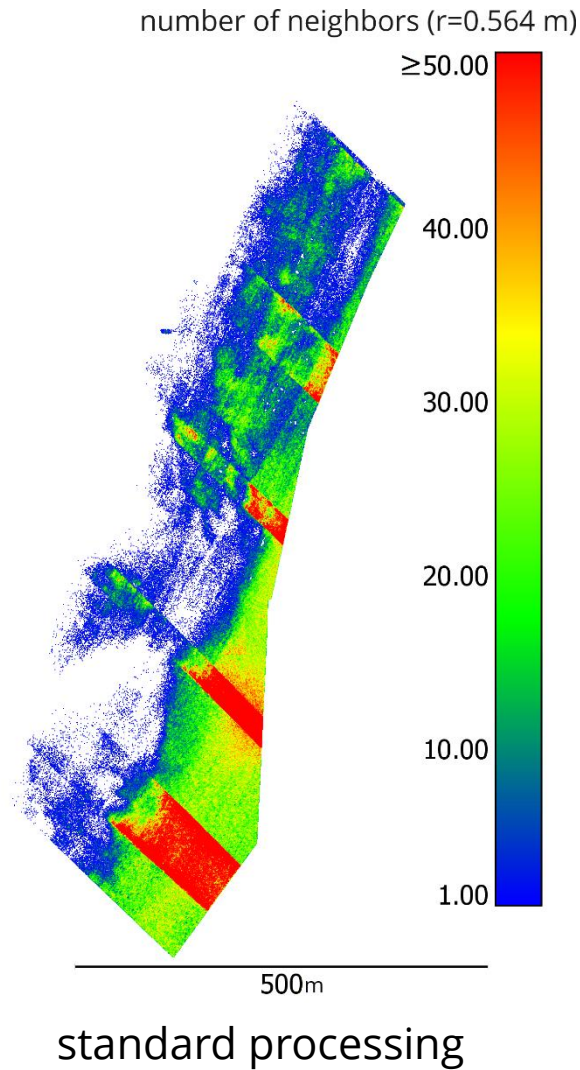
height differences: — OWP — sigFWFS — volFWFS
 number of points: - - OWP - - sigFWFS - - volFWFS

$|\Delta h| \leq 25$ cm: — OWP — sigFWFS — volFWFS
 number of points: - - OWP - - sigFWFS - - volFWFS

(OWP = standard processing)

Source: Mader et al. 2023IHR

Results – additional information



| | standard | sigFWFS | volFWFS |
|---------------------|----------|----------------|-----------------|
| area comparison | 100 % | 111.4 % | 114.6 % |
| reached water depth | 2.87 m | 3.56m (+24.0%) | 3.62 m (+26.1%) |

(for areas with a point density ≥ 5 points/m²)

Source: Mader et al. 2023|HR

Publications regarding full-waveform stacking processing methods

signal-based full-waveform stacking (PFG Journal):

- Mader, D., Richter, K., Westfeld, P. & Maas, H. (2021). Potential of a Non-linear Full-Waveform Stacking Technique in Airborne LiDAR Bathymetry. *PFG – Journal Of Photogrammetry Remote Sensing And Geoinformation Science*, 89(2), 139–158. <https://doi.org/10.1007/s41064-021-00147-y>

volumetric full-waveform stacking (ISPRS Journal):

- Mader, D., Richter, K., Westfeld, P. & Maas, H. (2023). Volumetric nonlinear ortho full-waveform stacking in airborne LiDAR bathymetry for reliable water bottom point detection in shallow waters. *ISPRS Journal Of Photogrammetry And Remote Sensing*, 204, 145–162. <https://doi.org/10.1016/j.isprsjprs.2023.08.014>

application to maritime water - North Sea (The International Hydrographic Review - IHR):

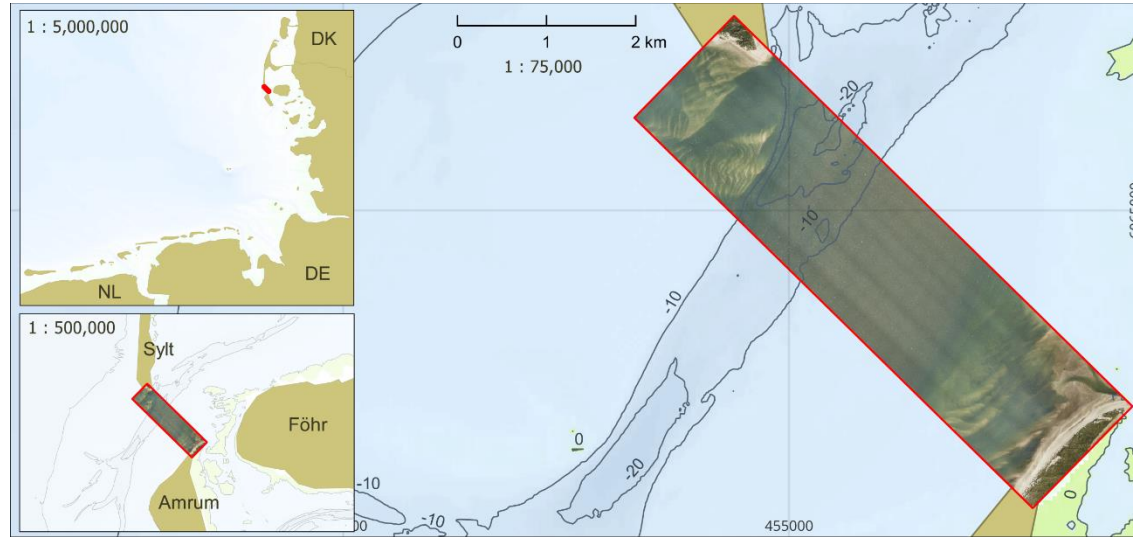
- Mader, D., Richter, K., Westfeld, P., Nistad, J. & Maas, H. (2023). Analysis of the potential of full-waveform stacking techniques applied to coastal airborne LiDAR bathymetry data of the German Wadden Sea National Park. *The International Hydrographic Review*, 29(2), 46–64. <https://doi.org/10.58440/ihr-29-2-a31>

For more information please contact: david.mader@tu-dresden.de

Research Project - Laser bathymetry in nearshore areas of the North Sea



project website (TUD)



project article in the IHR



Dr.-Ing. David Mader
TU Dresden



Dr.-Ing. Katja Richter
TU Dresden



Dr.-Ing. Patrick Westfeld
BSH Rostock



Prof. Dr. habil Hans-Gerd Maas
TU Dresden